



## Checklists - Page 1 - Parameters

Company:	_____	Date:	_____
Address:	_____	Phone:	_____
Contact:	_____	Fax:	_____
Dept.:	_____	E-mail:	_____

## 1 Lifting force in kN, max.

- Per gearbox [\_\_\_\_\_] kN    Per system [\_\_\_\_\_] kN
- Under tension [\_\_\_\_\_] kN    Under compression [\_\_\_\_\_] kN
- Load: static [\_\_\_\_\_] kN    Dynamic [\_\_\_\_\_] kN
- Fitting posn.:  vertical     horizontal     pivotal
- Conditions:  smooth     impact load     vibrations

**Fast and efficient:**  
 → Copy  
 → Select  
 → Fax / E-mail  
 (Contacts: Section 10)

## 2 Lift / travel [\_\_\_\_\_] mm

## 3 Lifting speed

- Type N = 1.5 m/min     Type L = 0.375 m/min
- Customer requirement [\_\_\_\_\_] m/min (many variants possible)

## 4 Operating period, operating cycle

[\_\_\_\_\_] lifts per day [\_\_\_\_\_] lifts per hour    hours per day:  8     16     24

[\_\_\_\_\_] % operating period (ED) relative to 10 min,

For ED > 10 % per 10 min, please specify cycle (e.g.: 5s up, 5s pause, 5s down, 30s pause)

5 Type S or R:  S standing spindle     R rotating spindle

## 6 Standard layout No. [\_\_\_\_\_] Measure MA1 [\_\_\_\_\_] MA2 [\_\_\_\_\_] MA3 [\_\_\_\_\_] MA4 [\_\_\_\_\_] MA5 [\_\_\_\_\_]

See standard layouts, Checklist Section 2.7 and 2.8 (for multiple systems)

7 Component list  YES     NO    See Checklist Section 2.5 or 2.6!8 Motor:  Rotary voltage motor AC     Brake motor AC     \_\_\_\_\_     Manual operation

Spring-compression brake     Incremental encoder     Linear measuring system     Limit switches (S version)

## 9 Application purpose / function description / branch

Description:

Operating conditions:  Dry     Humid     Dusty     Chips     \_\_\_\_\_

Ambient temperature: Min. [\_\_\_\_\_] °C    Max. [\_\_\_\_\_] °C

10 Quantity: [\_\_\_\_\_] pcs.     Prototype first

## 11 Schedule: Quotation: [\_\_\_\_\_]    Delivery: [\_\_\_\_\_]

